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Development of Bipedal and Quadrupedal Locomotion in Humans from a Dynamical Systems Perspective
Äœner Tan (Honorary Member of the Turkish Academy of Sciences, Ankara, Turkey) Ä†ukurova University,
Medical School, Department of Physiology, Adana Turkey 1. Introduction Locomotion is the movement of an
organism fr om one place to another, often by the action of appendages such as flagella ...

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Quadrupedal locomotion, walking on all four extremities, is the most remarkable trait of the quadruped
animals, and has been elegantly elaborated by dynamic selection processes over millions of years.

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quadrupedal robot. We choose the Center of Mass dynamics and the full kinematic formulation as the
switched system model where the switching times as well as the contact forces and the joint velocities are
optimized for different locomotion tasks such as gap crossing, walking and trotting. I. INTRODUCTION
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The coordination of forelimb and hindlimb rhythmic activities is a main characteristic feature of quadrupedal
locomotion . Specialized neural circuits located in the caudal spinal cord [the so-called central pattern
generator (CPG) for locomotion] organize hindlimb locomotor activity, whereas specialized circuits in the
rostral spinal cord ...

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